

In re Patent Application of:  
**TOWNSEND ET AL.**  
Serial No. 10/538,019  
Filed: June 7, 2005

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**In the Claims:**

Claims 1-10 (Cancelled).

11. (Previously Presented) A method of automated pallet repair, comprising the steps of:

using a scanning device to create a three-dimensional data map of a pallet for detecting gaps and protrusions in the pallet, the scanning device generating a laser beam projected onto the pallet;

filtering the three-dimensional data map into a two-dimensional image of on/off values by using a dynamically created height value, corresponding to a reference plane or set threshold offset above a board surface of the pallet;

creating a recipe of repair operations from the three-dimensional data map; and

gripping the pallet and transporting the gripped pallet to one or more repair stations in accordance with the recipe.

Claim 12 (Cancelled).

13. (Previously Presented) The method of claim 11, further comprising filtering the three-dimensional data map with a Sobel or Gaussian filter to provide locations of the gaps and protrusions in the pallet.

Claims 14-16 (Cancelled).

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17. (Previously Presented) A method of automated pallet repair, comprising the steps of:

using a scanning device to create a three-dimensional data map of a pallet for detecting gaps and protrusions in the pallet;

filtering the three-dimensional data map into a two-dimensional image of on/off values by using a dynamically created height value, corresponding to a reference plane or set threshold offset above a board surface of the pallet;

creating a recipe of repair operations from the three-dimensional data map; and

transporting the pallet to at least one repair station in accordance with the recipe.

18. (Previously Presented) The method of claim 17, further comprising filtering the three-dimensional data map with a Sobel or Gaussian filter to provide locations of the gaps and protrusions in the pallet.

19. (Previously Presented) The method of claim 17, wherein the scanning device generates a laser beam projected onto the pallet.

20. (Currently Amended) A method of automated pallet repair, comprising the steps of:

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using a scanning device to generate generating a three-dimensional data map of a pallet, the three-dimensional data map including features, dimensions and topography of the pallet;

filtering the three-dimensional data map into a two-dimensional image comprising on/off values by using a dynamically created height value corresponding to a reference plane above a board surface of the pallet;

generating a recipe of repair operations based on the filtered three-dimensional data map; and

transporting the pallet to at least one repair station based on the recipe.

Claims 21-24 (Cancelled).

25. (Currently Amended) The method of ~~claim 21~~ claim 20, further comprising filtering the three-dimensional data map with a Sobel or Gaussian filter to provide locations of gaps and protrusions in the pallet.

26. (Previously Presented) The method of claim 20, further comprising gripping the pallet before transporting the pallet to the at least one repair station.

27. (New) A method of automated pallet repair, comprising the steps of:

using a scanning device to generate a three-dimensional data map of a pallet, the three-dimensional data map including features, dimensions and topography of the pallet;

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filtering the three-dimensional data map into a two-dimensional image comprising on/off values by using a dynamically created height value corresponding to set threshold offset above a board surface of the pallet;

generating a recipe of repair operations based on the filtered three-dimensional data map; and

transporting the pallet to at least one repair station based on the recipe.

28. (New) The method of claim 27, further comprising filtering the three-dimensional data map with a Sobel or Gaussian filter to provide locations of gaps and protrusions in the pallet.

29. (New) The method of claim 27, further comprising gripping the pallet before transporting the pallet to the at least one repair station.